

Reinforcement Learning For Autonomous Quadrotor Helicopter

Relatively simple individual rules can produce a large set of complex swarm behaviors. A key component is the communication between the members of the group that build a system of constant feedback. The swarm behavior involves constant change of individuals in cooperation with others, as well as the behavior of the whole group. 8e412866c1

Swarm robotics ; Kumar, V. ; Powers, C. Mellinger, D. The emerging swarming behavior of robotic swarms is created through the interactions between individual robots and the environment. This idea emerged on the field of artificial swarm intelligence, as well as the studies of insects, ants and other fields in nature, where swarm behavior occurs. , "Towards a swarm of agile micro quadrotors" Autonomous Robots, Volume 35, Issue 4, pp 287-300, November 2013 Vasarhelyi Swarm robotics is the study of how to design independent systems of robots without centralized control 8e412866c1

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